

Amendments to the Abstract:

The Abstract, at page 26, is to be amended as follows:

Abstract

A robot is provided which is adapted to operate in association with an interface surface ~~having, which~~ has disposed therein or thereon coded data indicative of an identity of the interface surface and of a plurality of reference points of the interface surface~~[[, the]]. The robot comprising:~~[(1)has movement means to allow the robot to move over the interface surface~~[[;(2)]]~~], a sensing device which senses at least some of the coded data and generates indicating data indicative of the identity of the interface surface and of a position of the robot on the interface surface[[; (3)]], and communication means to[[:(A)]] transmit the indicating data to a computer system;~~the computer system which is programmed to select and execute a computer application based on at least the identity of the interface surface; and, (B), and to receive movement instructions from the selected computer application, whereby, the.~~ The behaviour of the robot is at least in part controlled by the selected computer application.